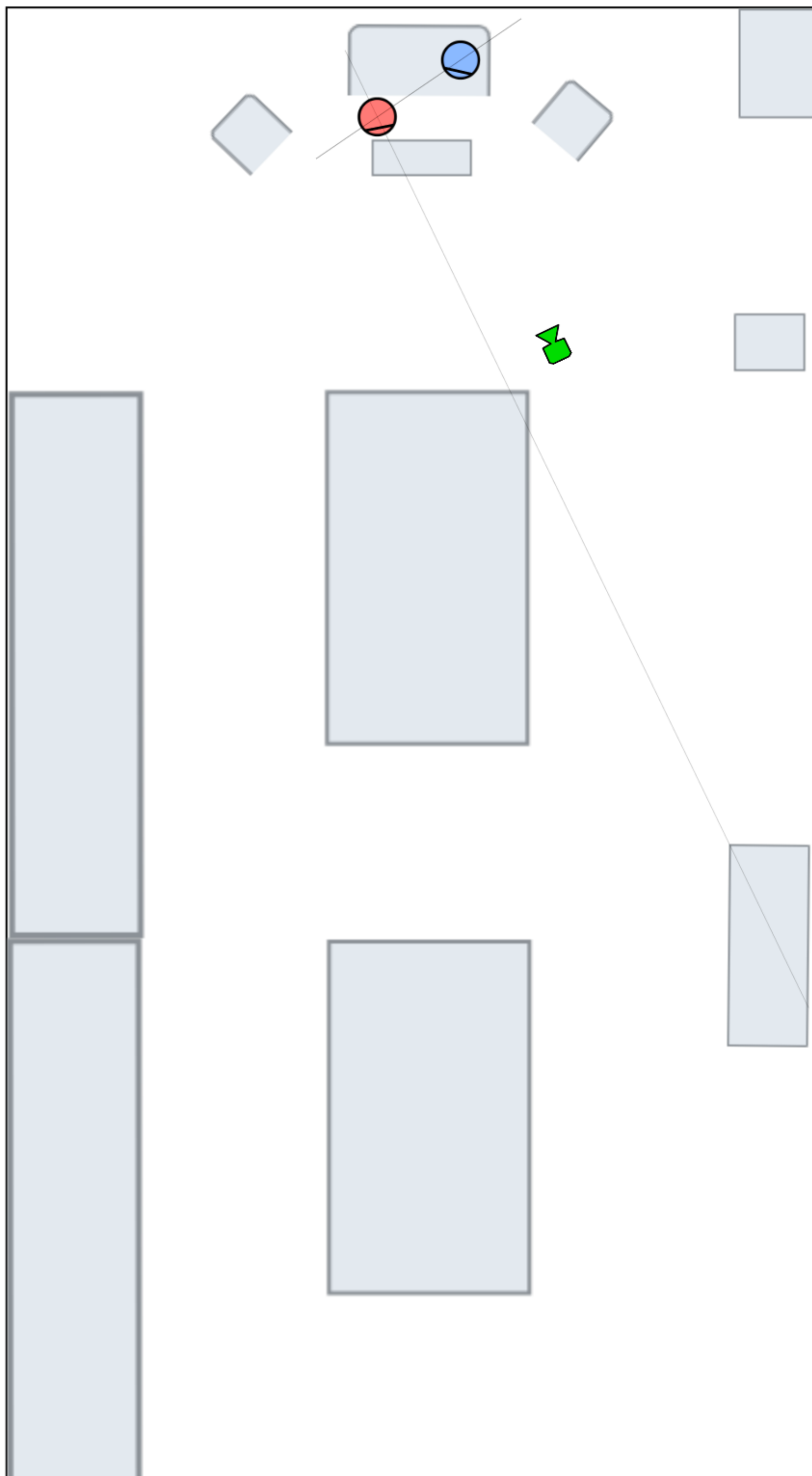
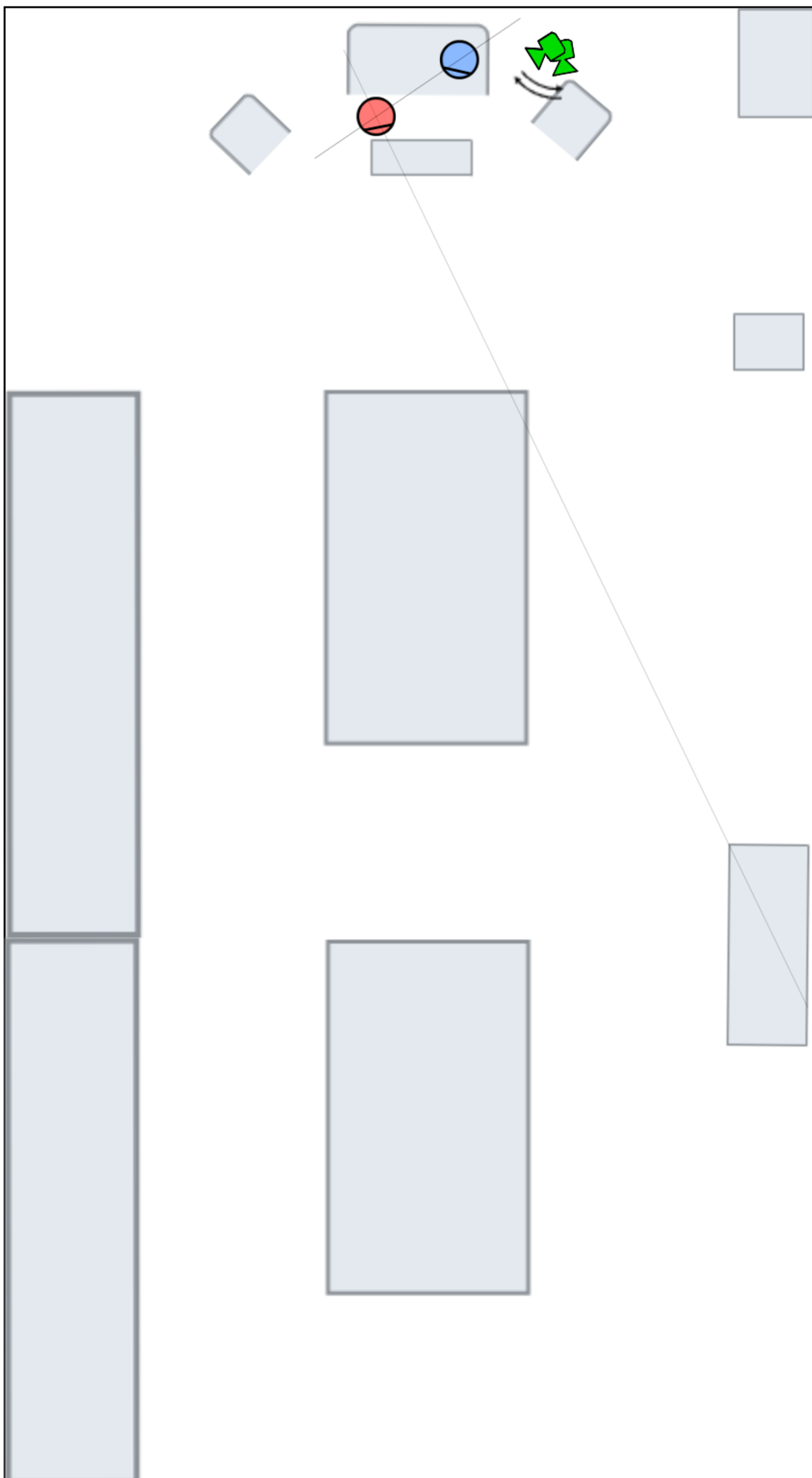


The diagram shows a 2D environment with several obstacles represented by gray rectangles. There are 12 green robot icons, each with a black dot and a number (1-12) indicating its position. A sequence of red arrows connects several of these robots, starting from robot 1 and ending at robot 12. The path starts at robot 1, goes to robot 2, then to robot 3, robot 4, robot 5, robot 6, robot 7, robot 8, robot 9, robot 10, robot 11, and finally to robot 12. The arrows indicate a specific sequence of movements or interactions between the robots in the environment.

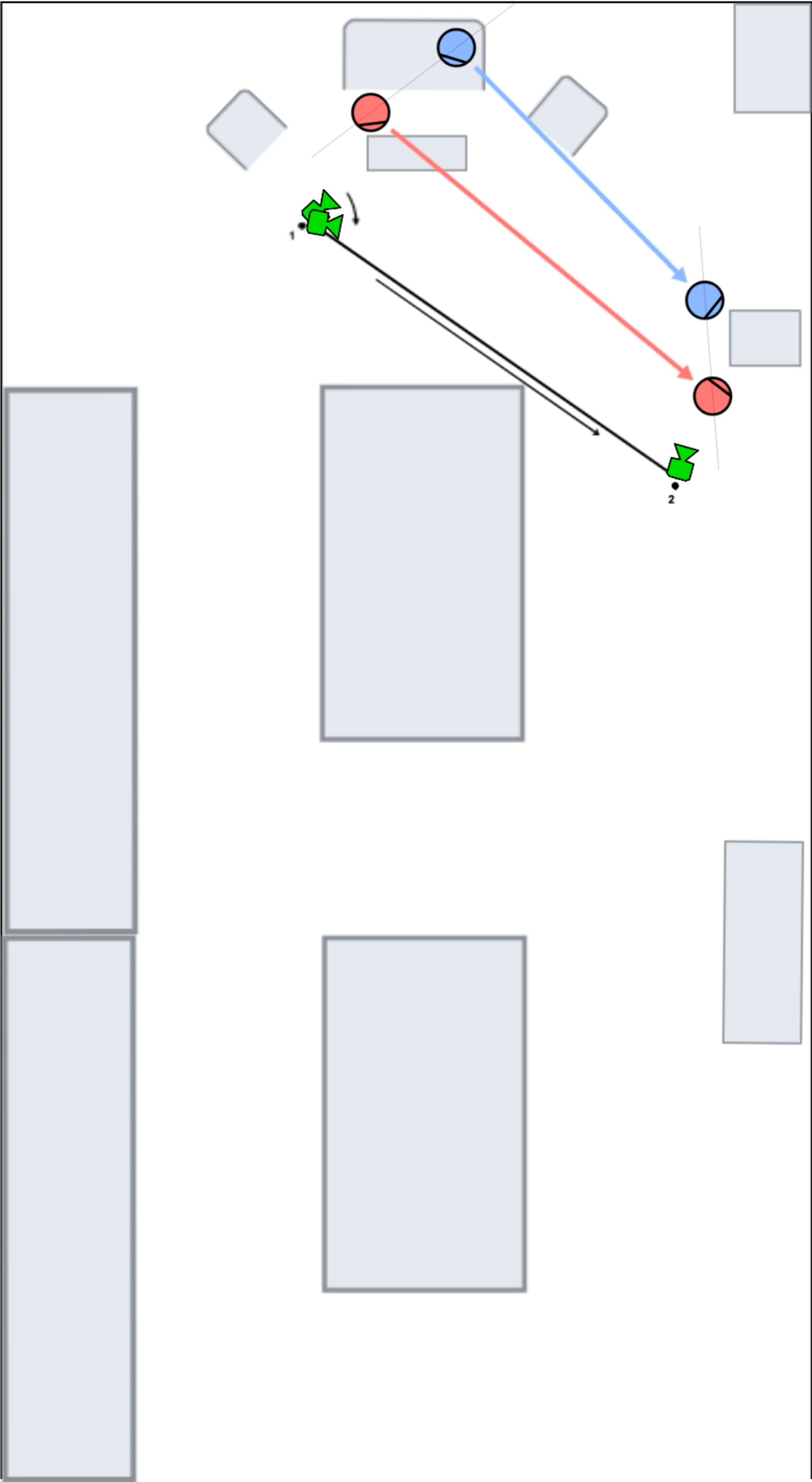
2.1



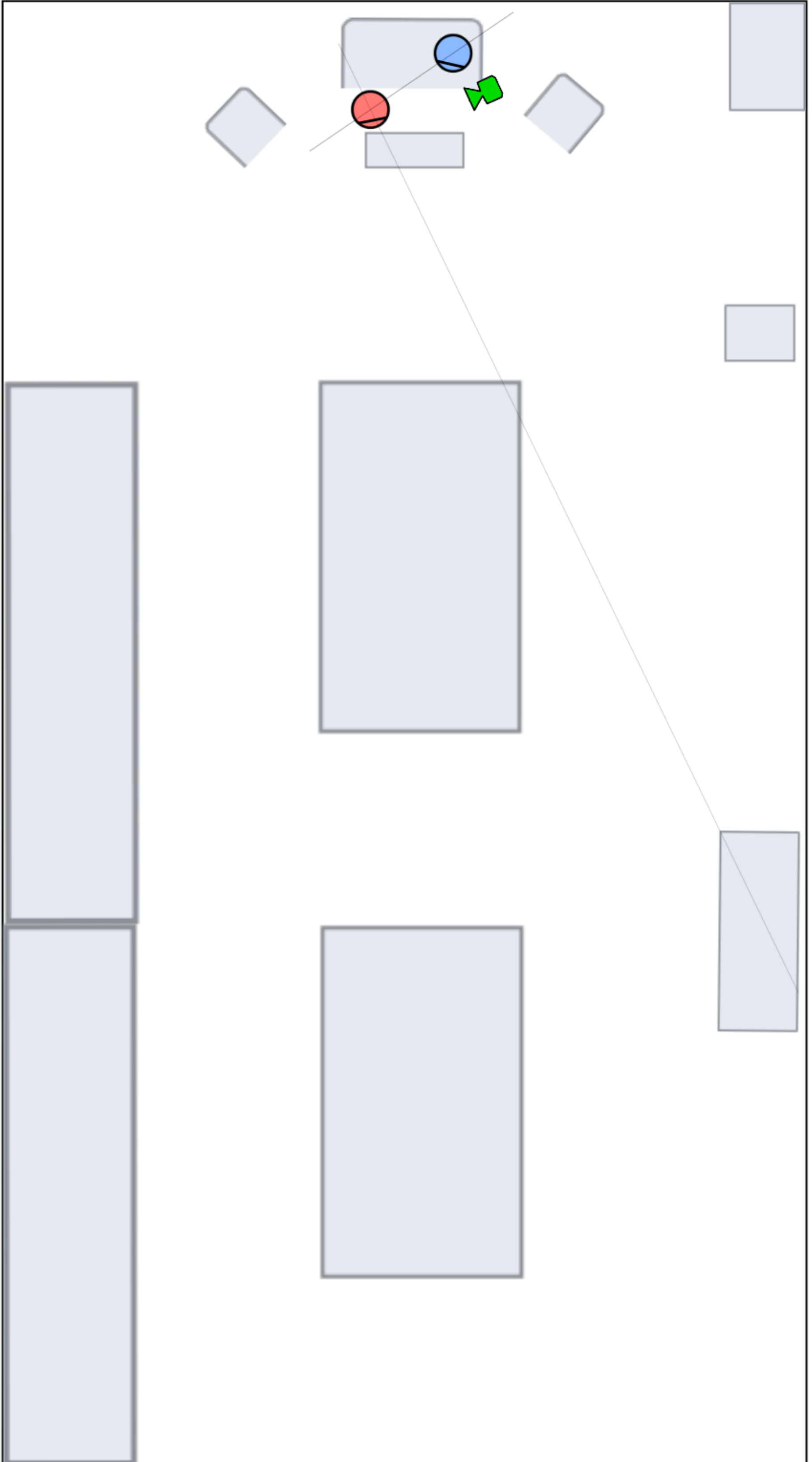
2.2



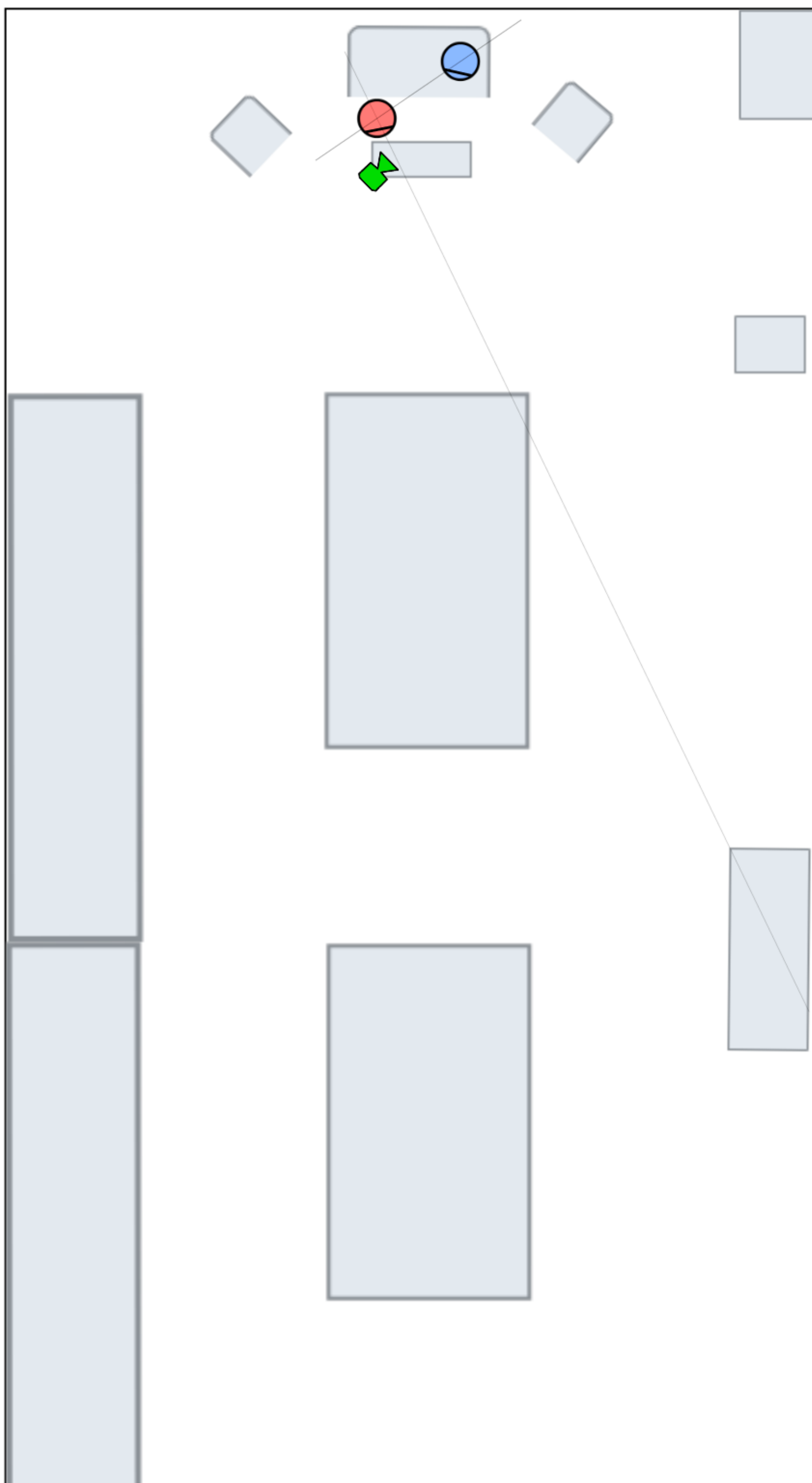
2.3



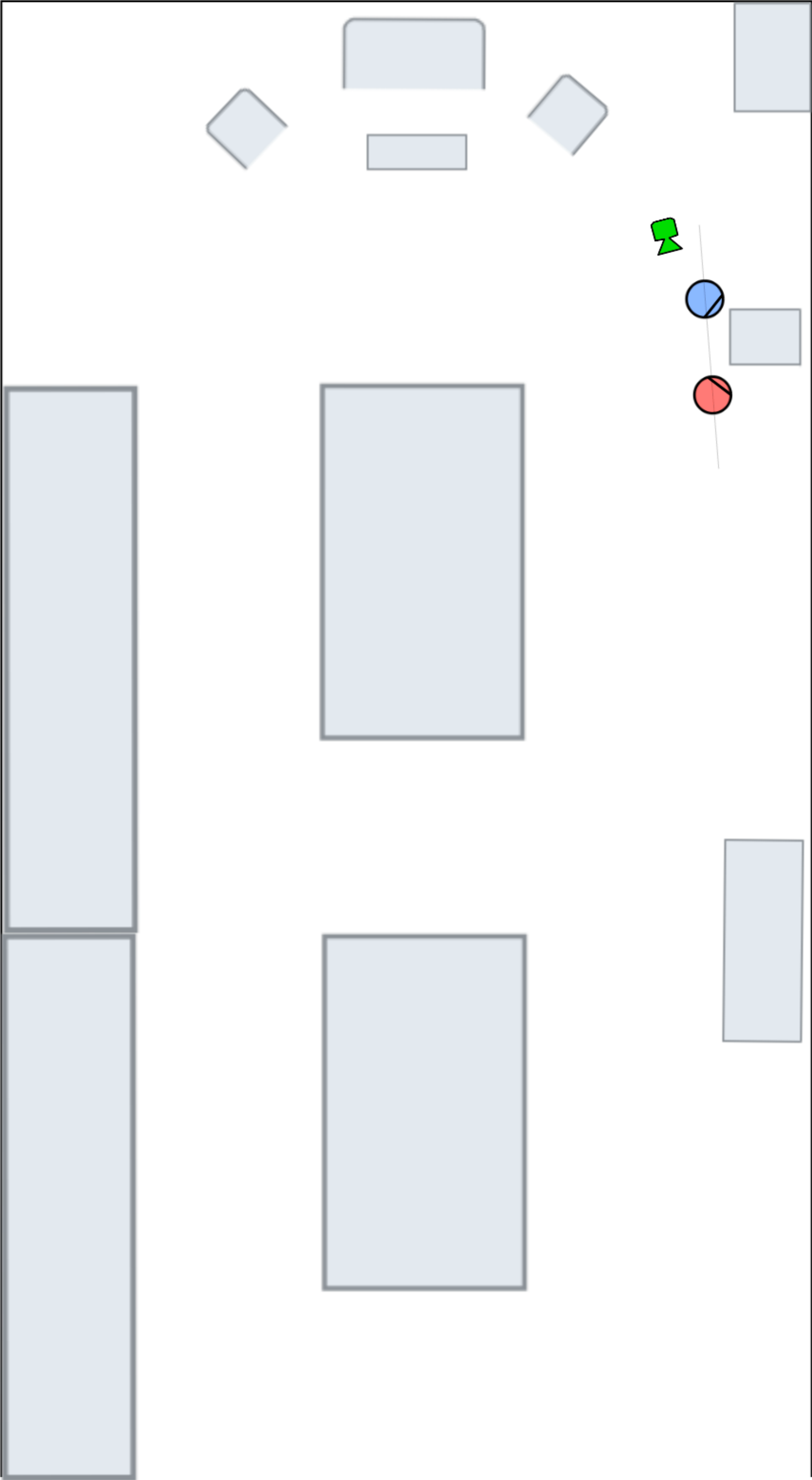
2.4



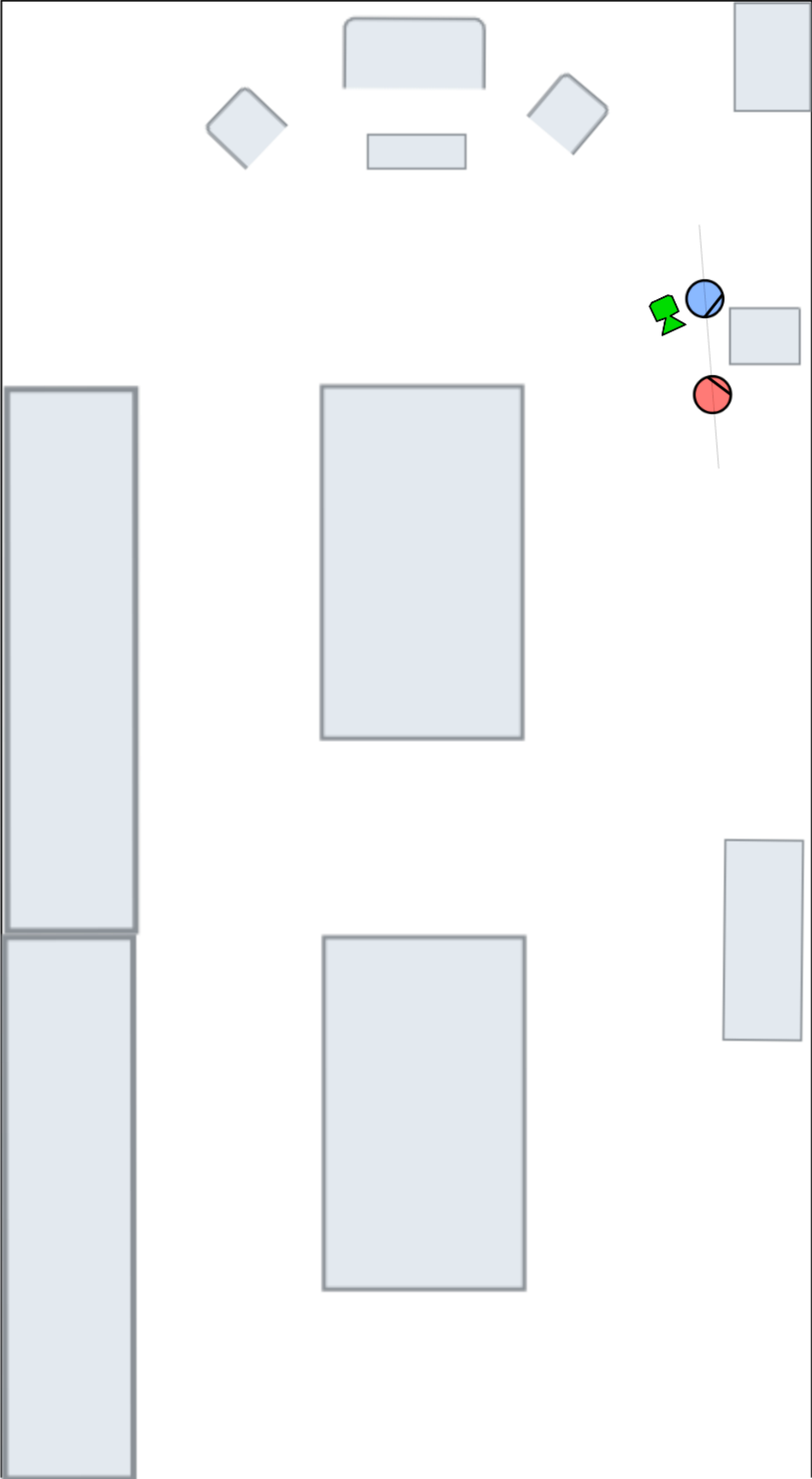
2.5



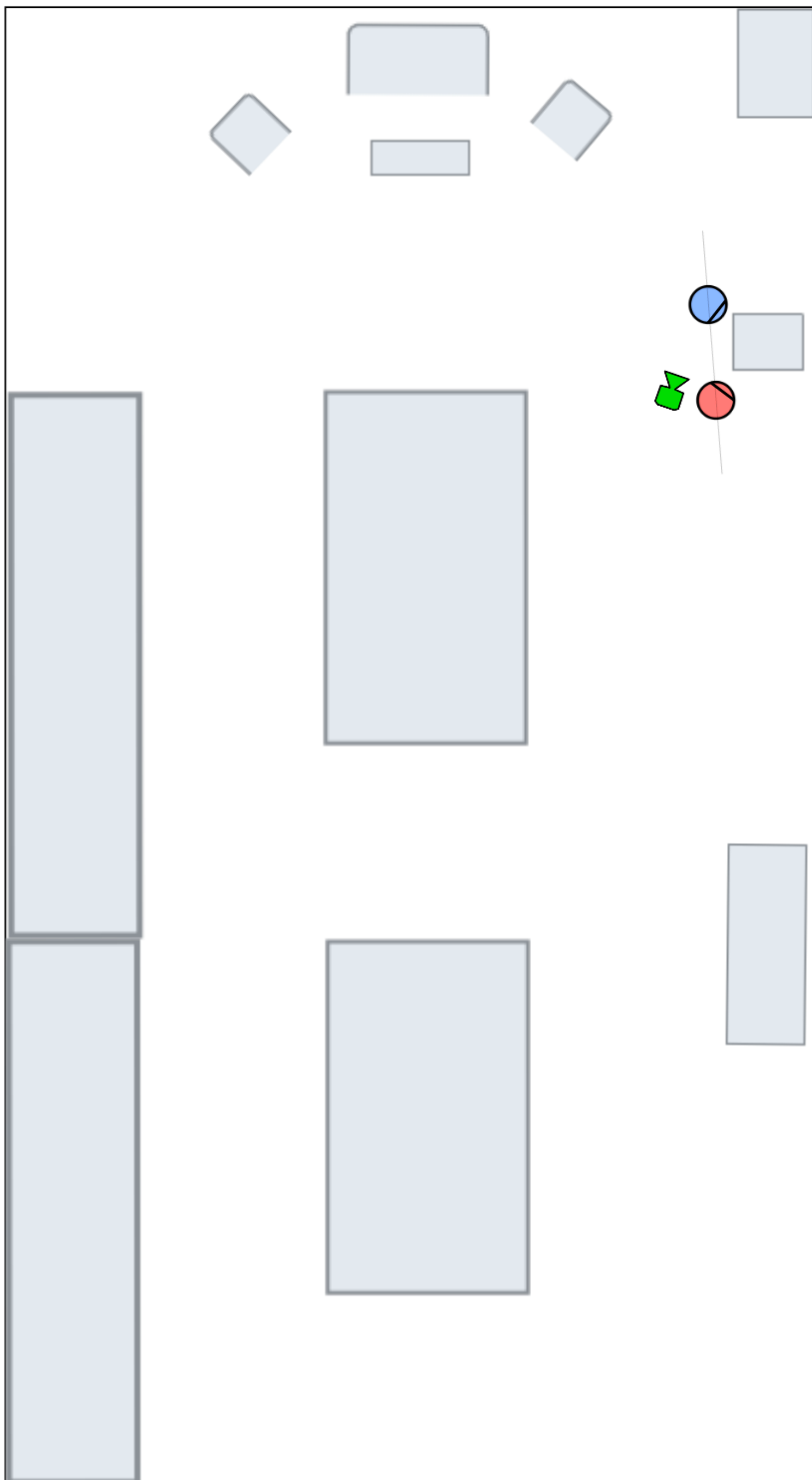
2.6



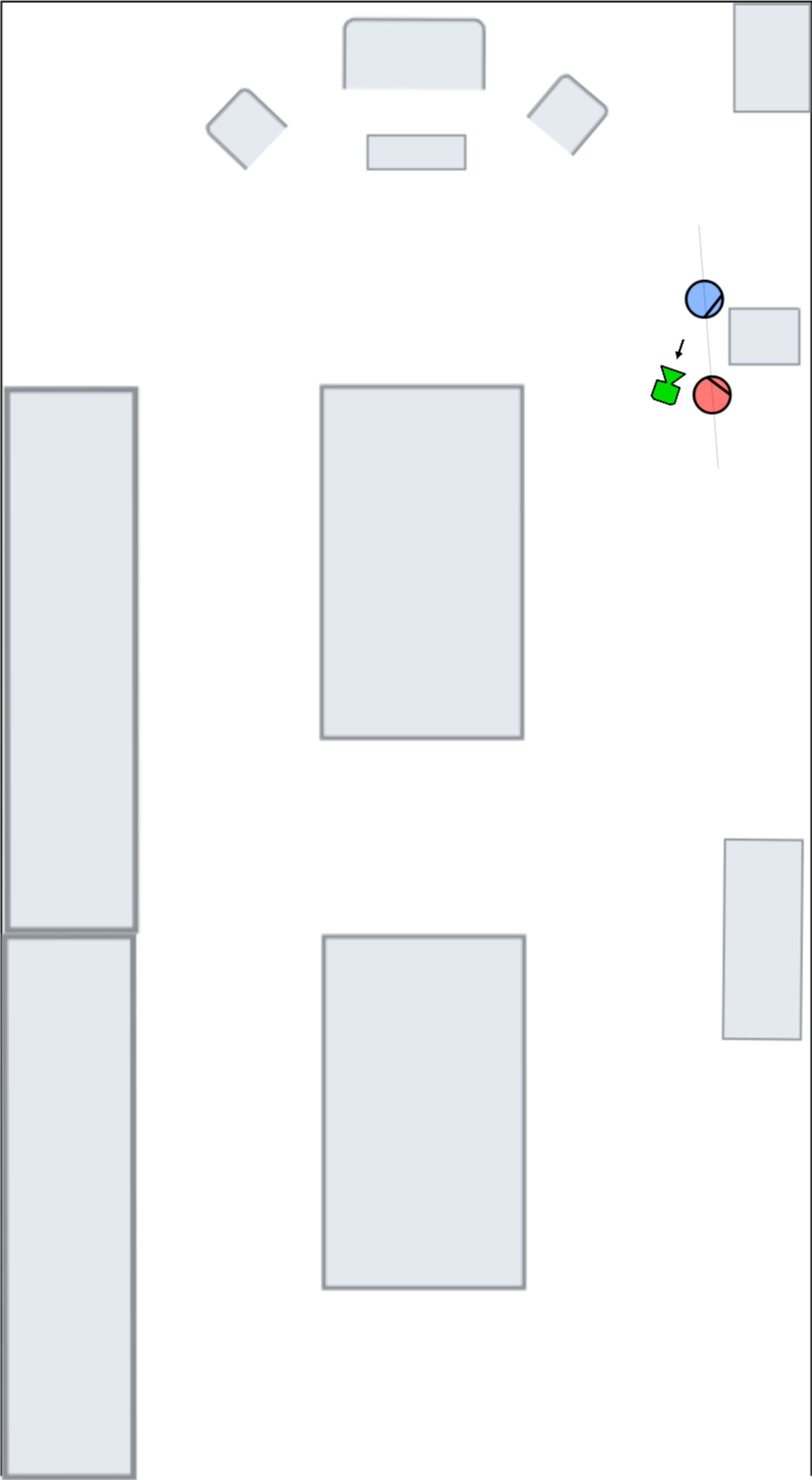
2.7



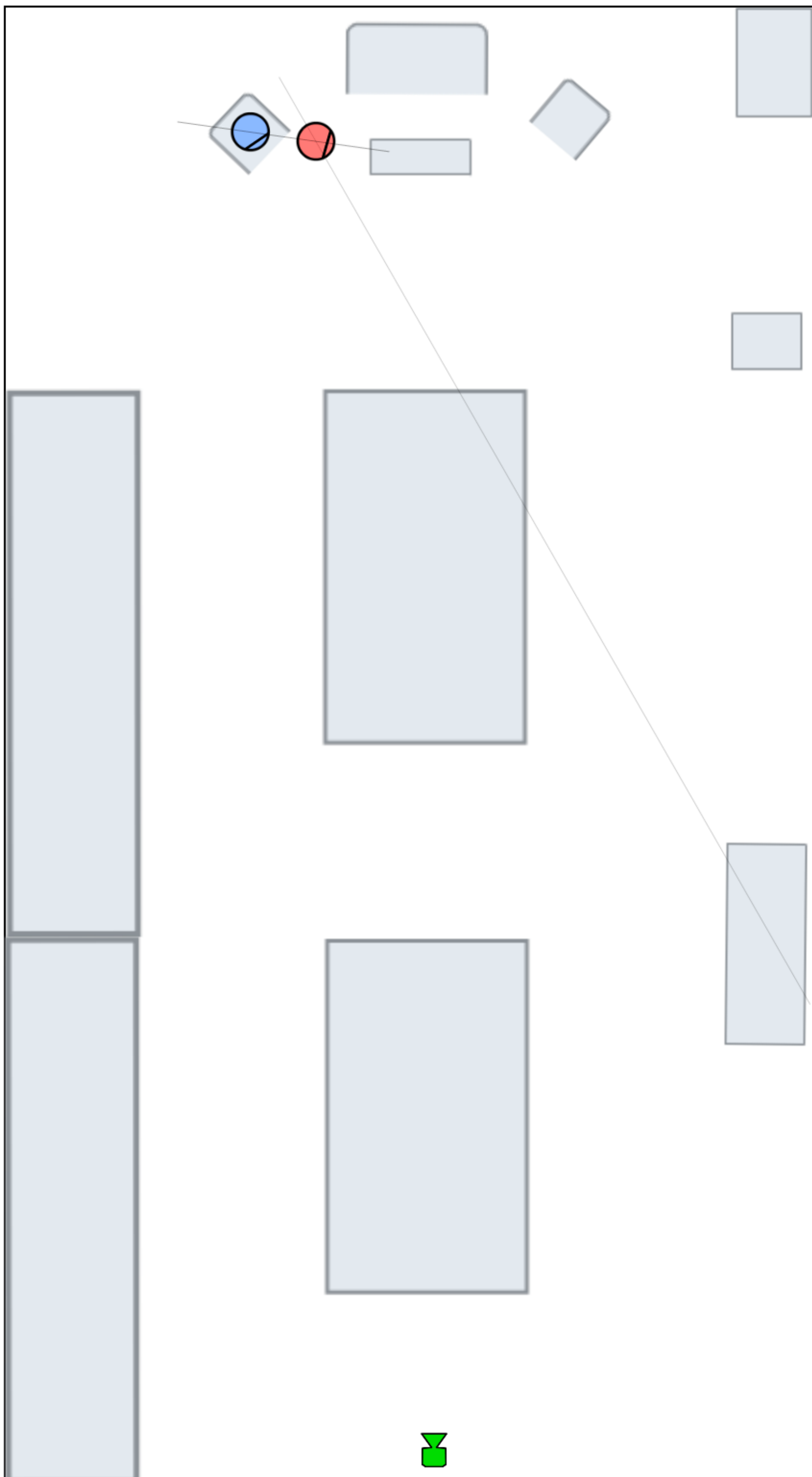
2.8



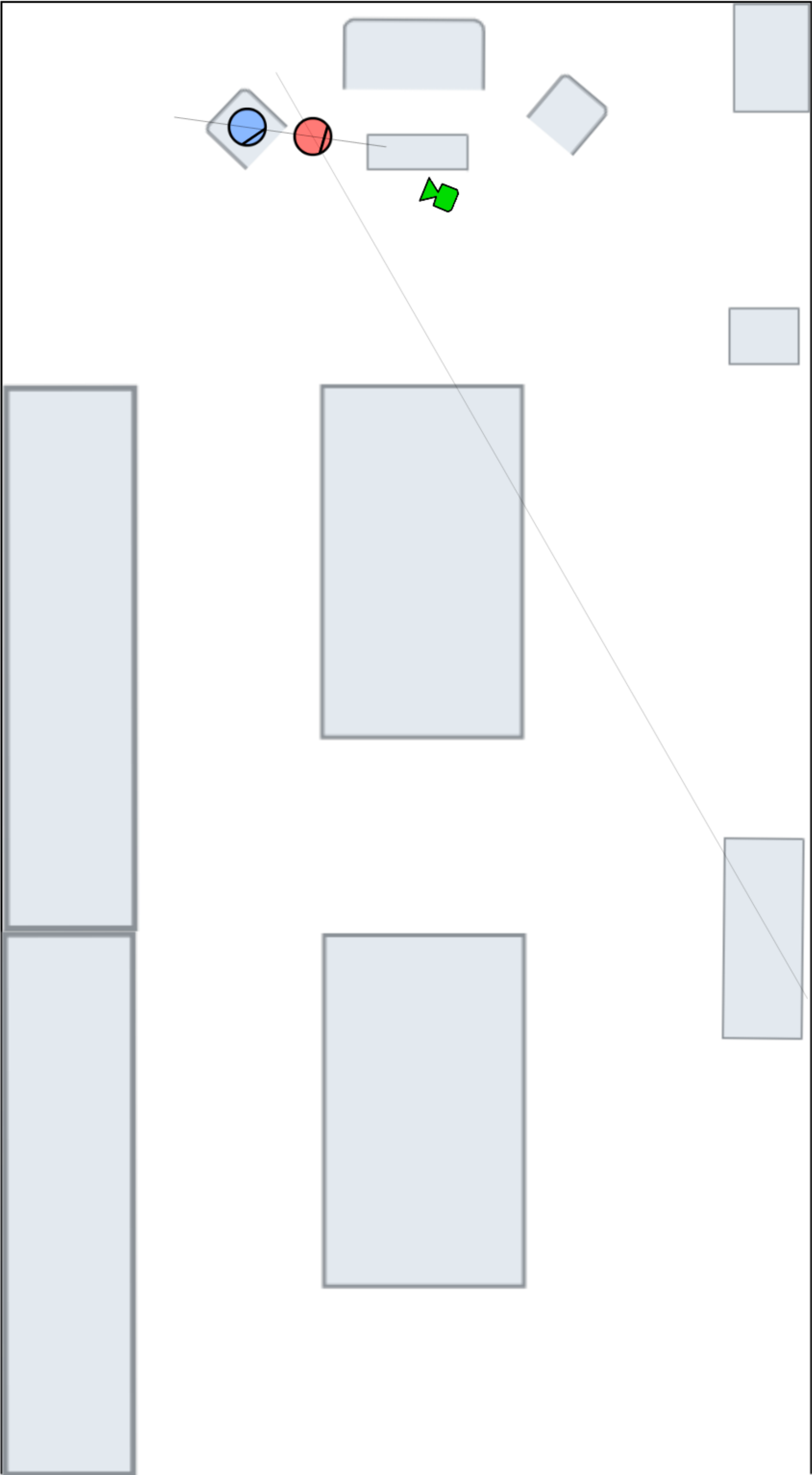
2.9



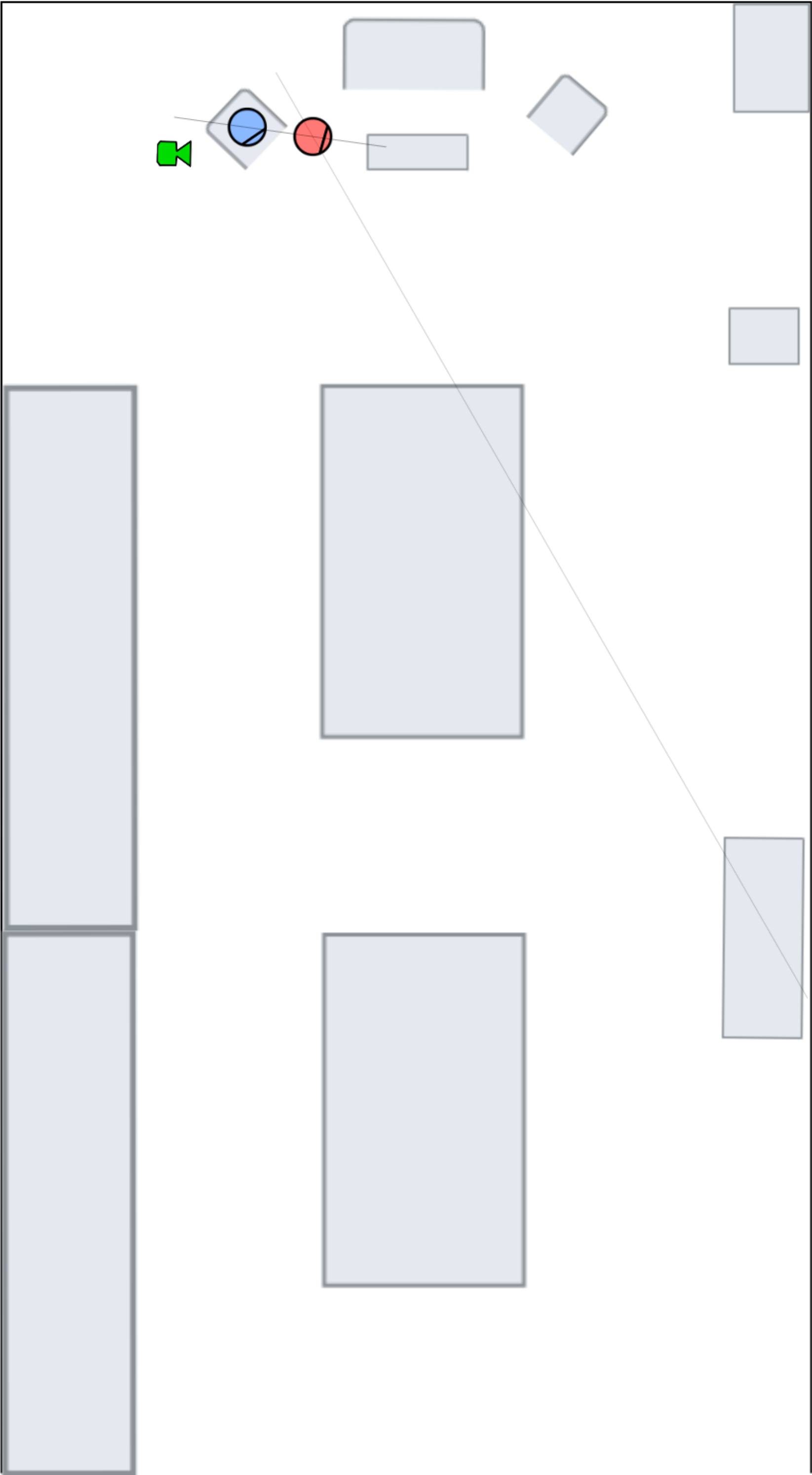
3.1



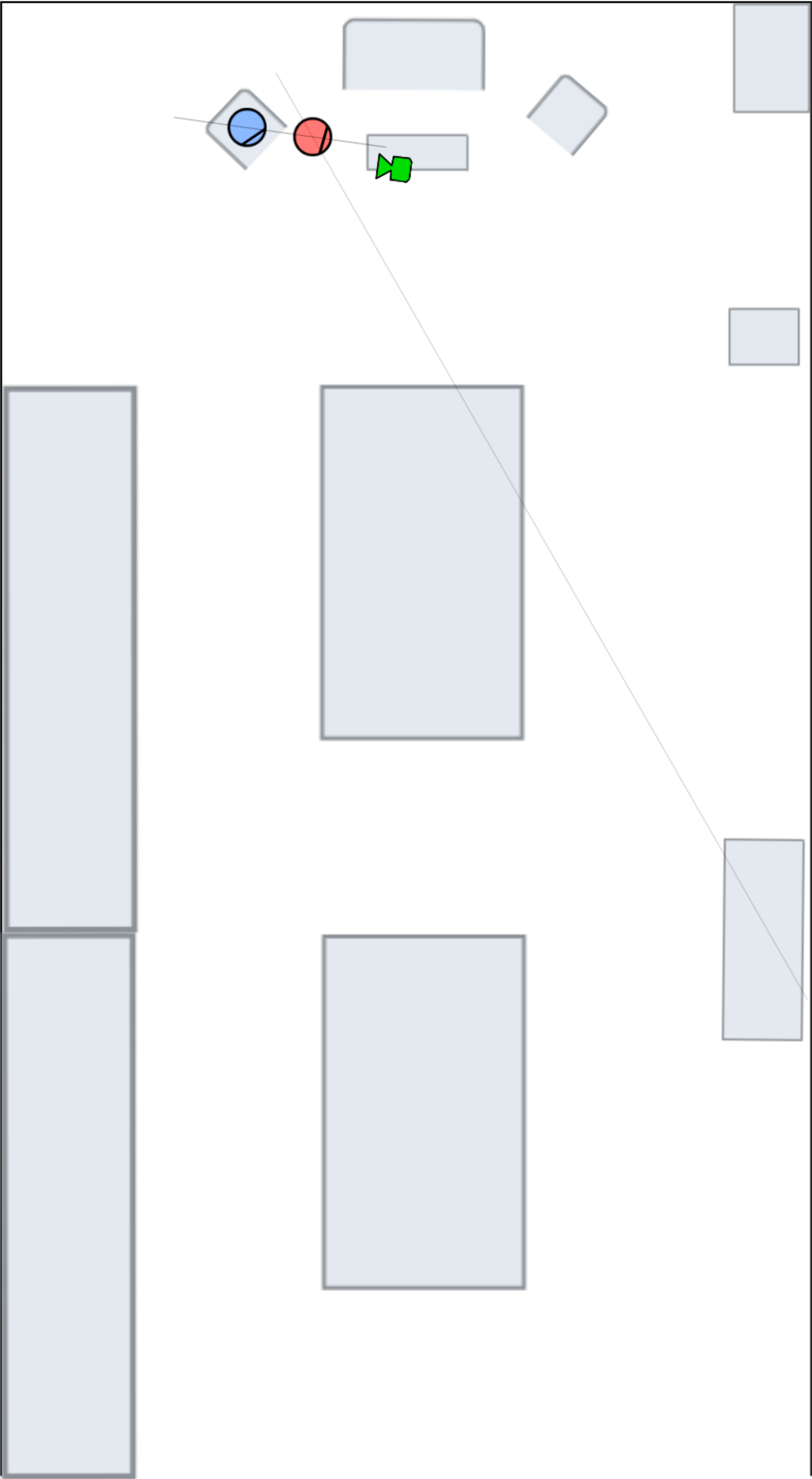
3.2



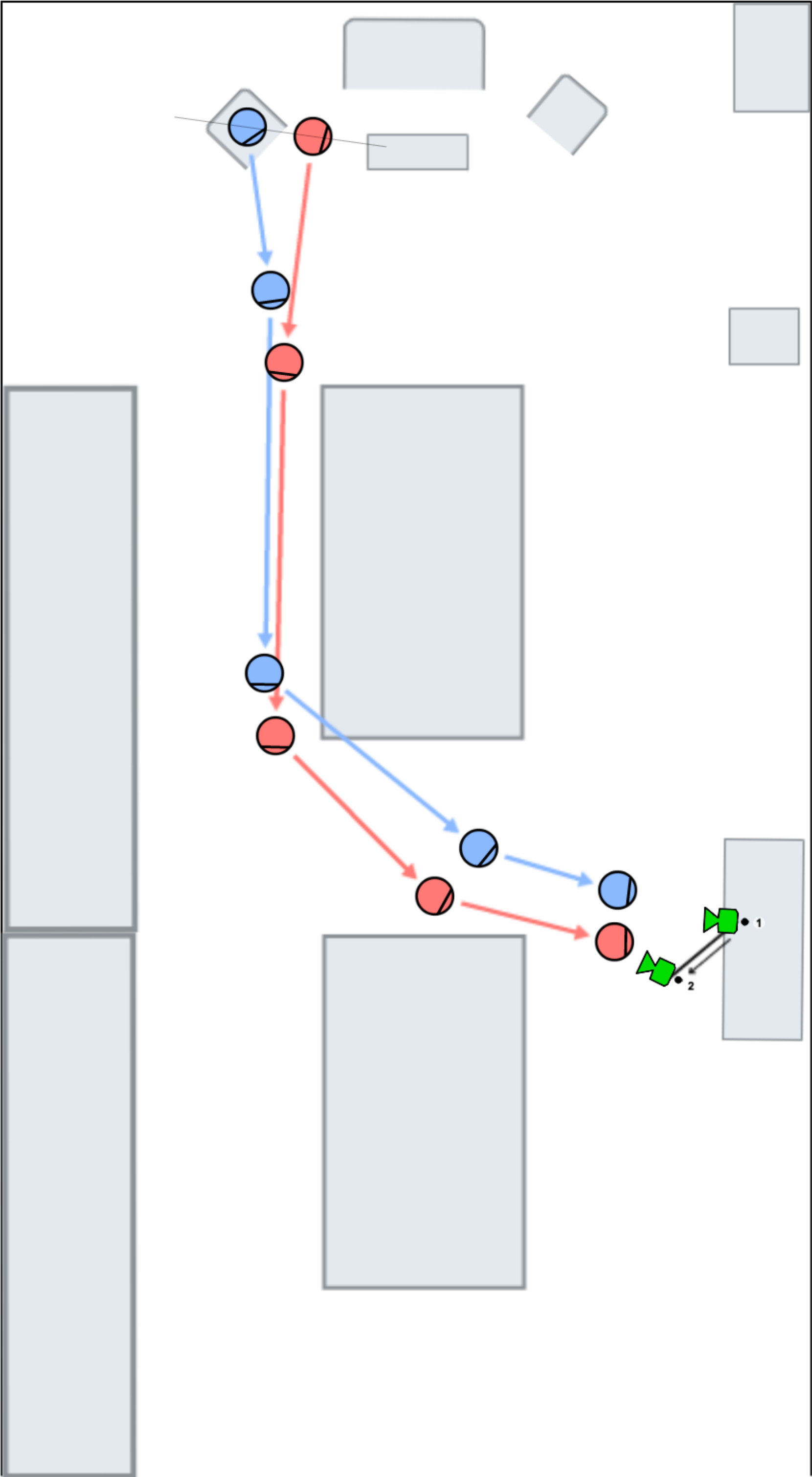
3.3



3.4



3.5



4.1

